



Design, Automation & Test in Europe
24-28 March, 2014 - Dresden, Germany

The European Event for Electronic
System Design & Test

IIR Filters Using Stochastic Arithmetic

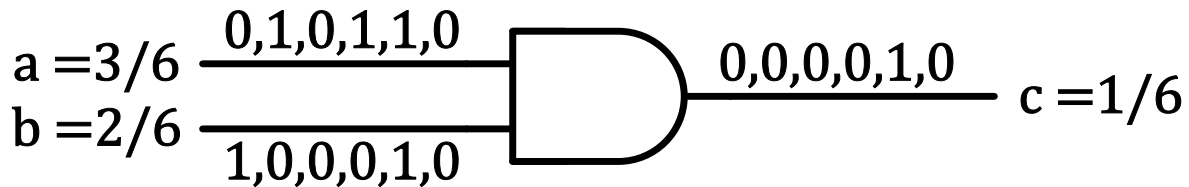
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David J Lilja and Marc D Riedel
University of Minnesota, Twin Cities

Outline

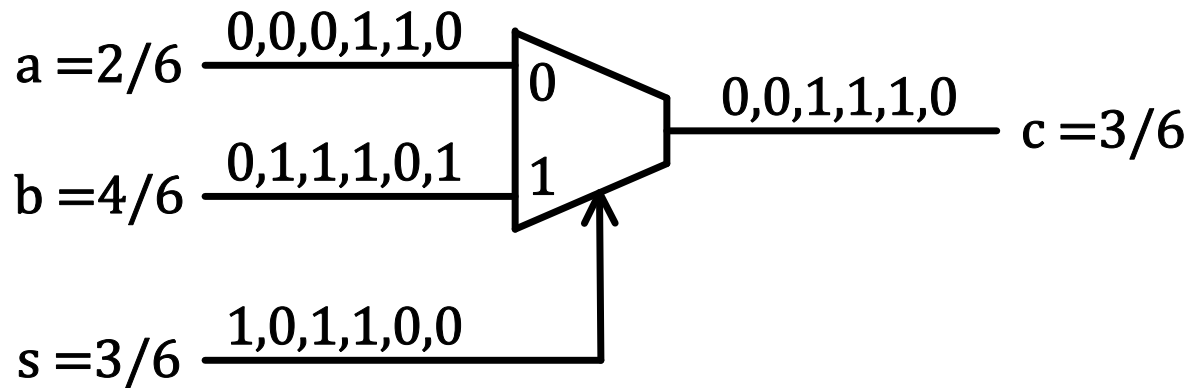
- **Introduction**
- **Stochastic Filtering**
- **Experiments and Results**
- **Conclusions and Future Research**

Introduction: Stochastic computing

- Computing using random bit streams.



$$c = ab$$



$$c = (1 - s)a + sb$$

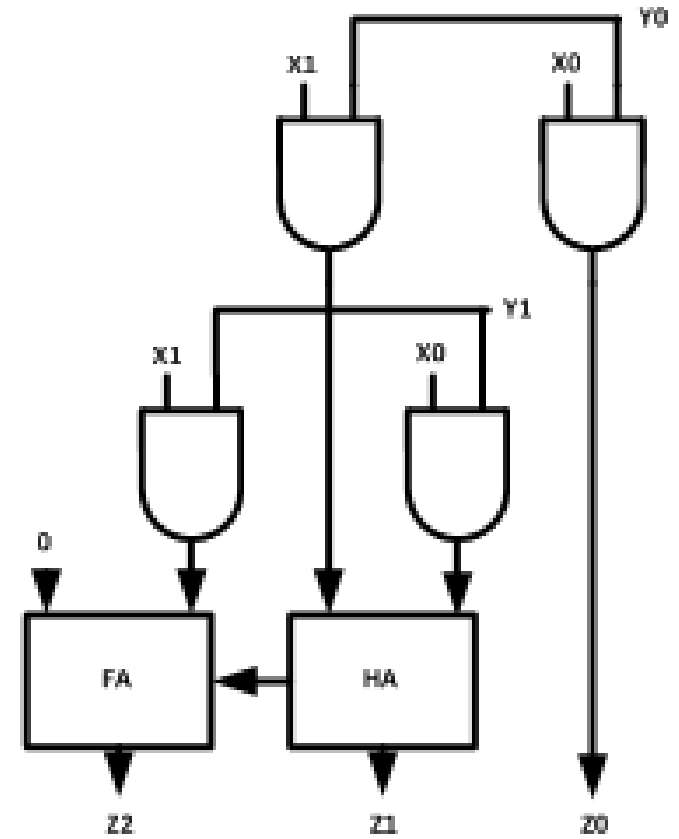
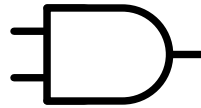
Stochastic computing: Area

Stochastic

Conventional

1 AND

7 AND + 3XOR + 1 OR



Stochastic computing: Fault Tolerance

- Largest error due to a single bit flip in an M -bit binary fraction is $1/2$

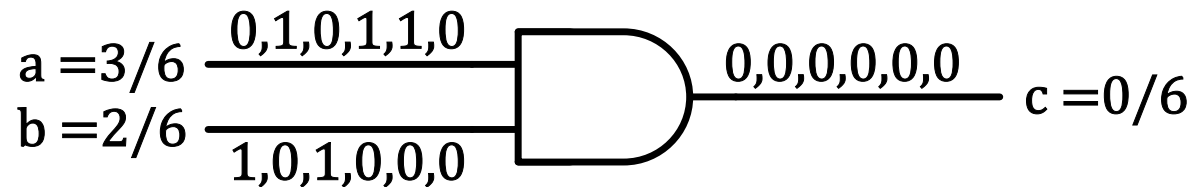
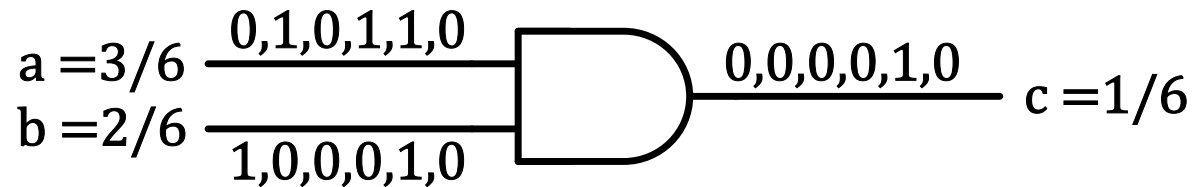
$$\begin{array}{ccc} 0.001 & \longrightarrow & 0.101 \\ (0.125) & & (0.625) \end{array}$$

- Largest error in a random bit stream of length 2^M due to a single bit flip is always 2^{-M} .

$$\begin{array}{ccc} 00100000 & \longrightarrow & 00100010 \\ (0.125) & & (0.250) \end{array}$$

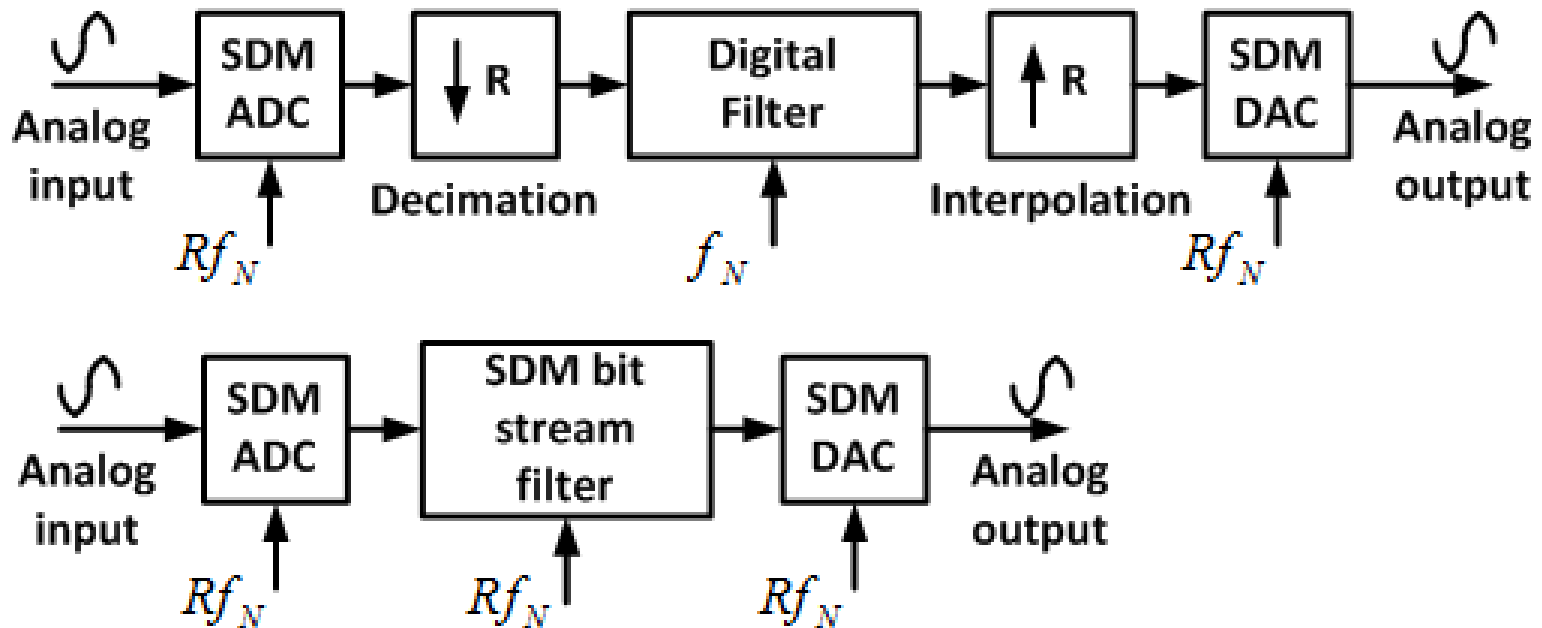
Stochastic computing: Accuracy

- Random representation

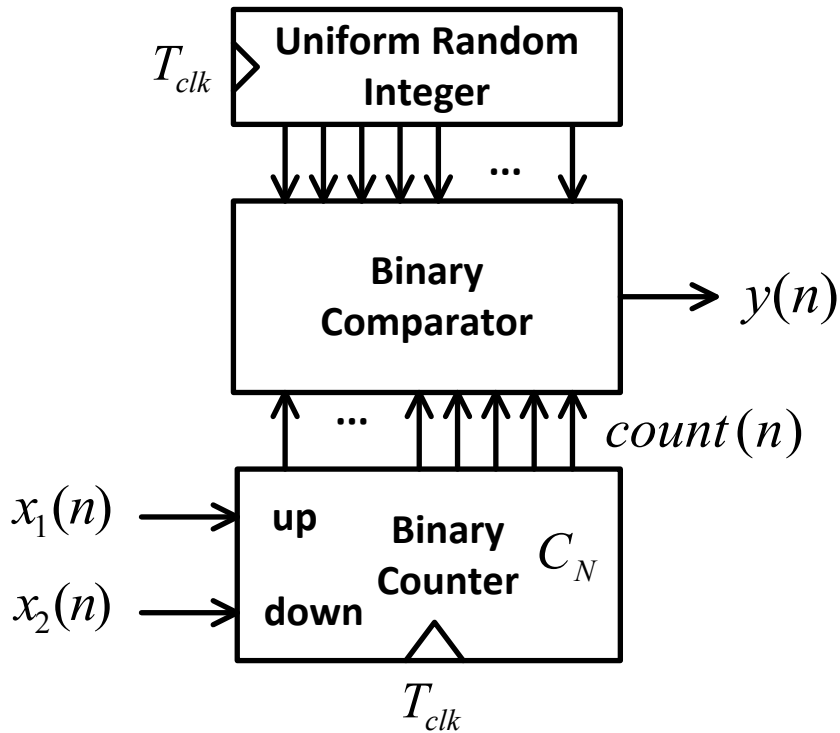


Stochastic Filtering: Motivation

- Reduce Area
 - Multi-bit v/s bit stream
 - Interface filters



Stochastic Integrator



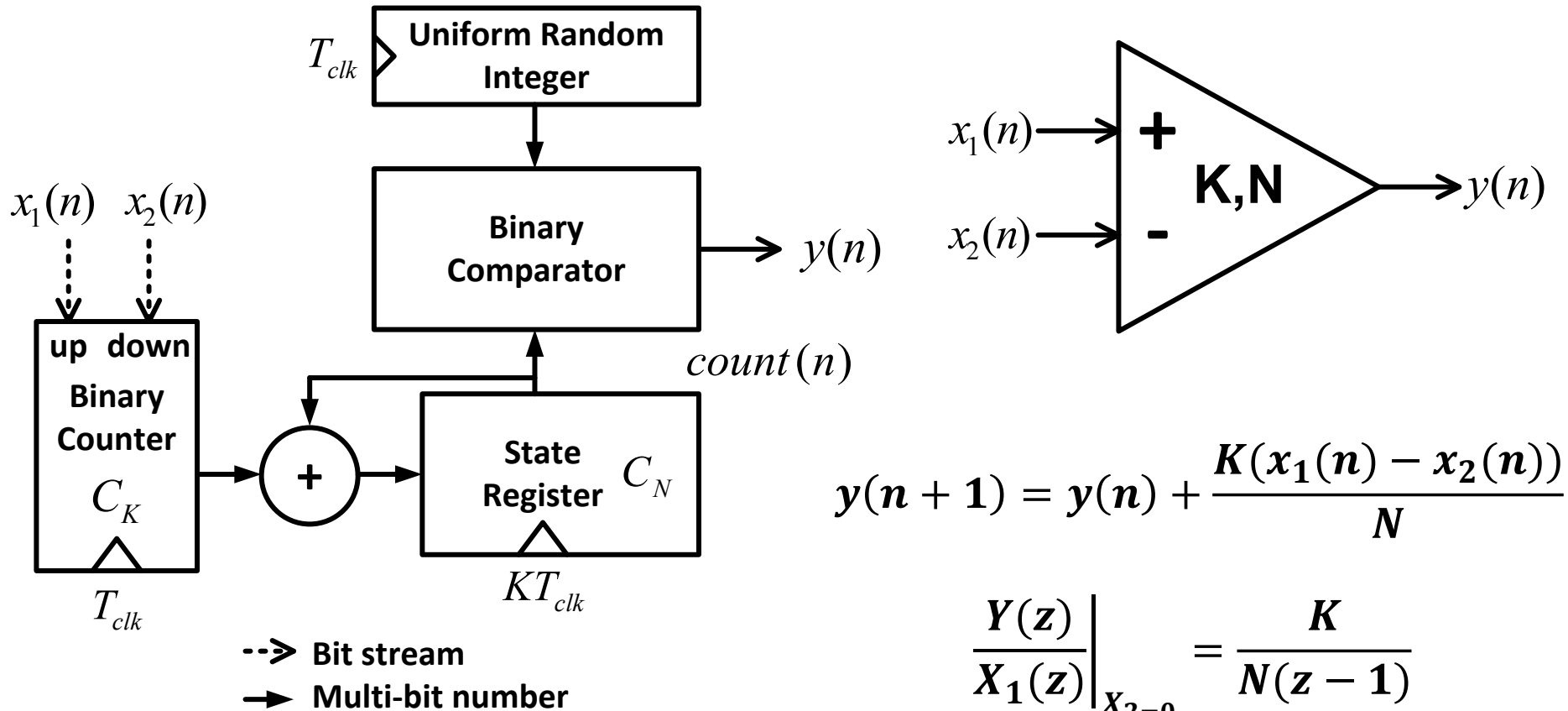
$$y(n+1) = y(n) + \frac{x_1(n) - x_2(n)}{N}$$

$$\left. \frac{Y(z)}{X_1(z)} \right|_{X_2=0} = \frac{1}{N(z-1)}$$

$$\left. \frac{Y(z)}{X_2(z)} \right|_{X_1=0} = \frac{-1}{N(z-1)}$$

[Gaines 1969]

Stochastic Integrator: Our Approach

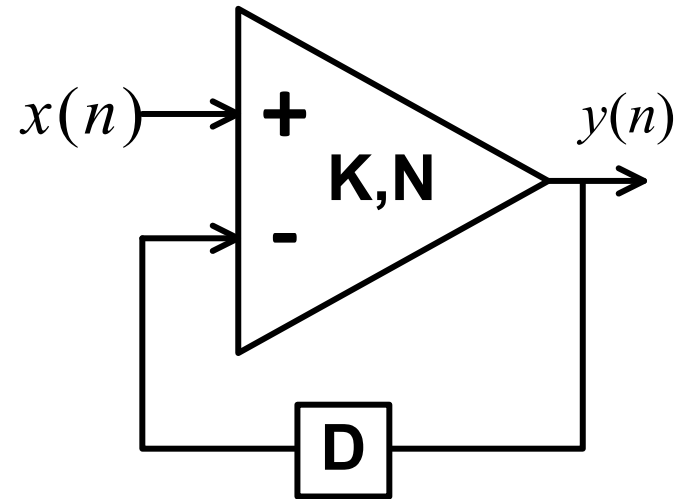


$$y(n+1) = y(n) + \frac{K(x_1(n) - x_2(n))}{N}$$

$$\left. \frac{Y(z)}{X_1(z)} \right|_{X_2=0} = \frac{K}{N(z-1)}$$

$$\left. \frac{Y(z)}{X_2(z)} \right|_{X_1=0} = \frac{-K}{N(z-1)}$$

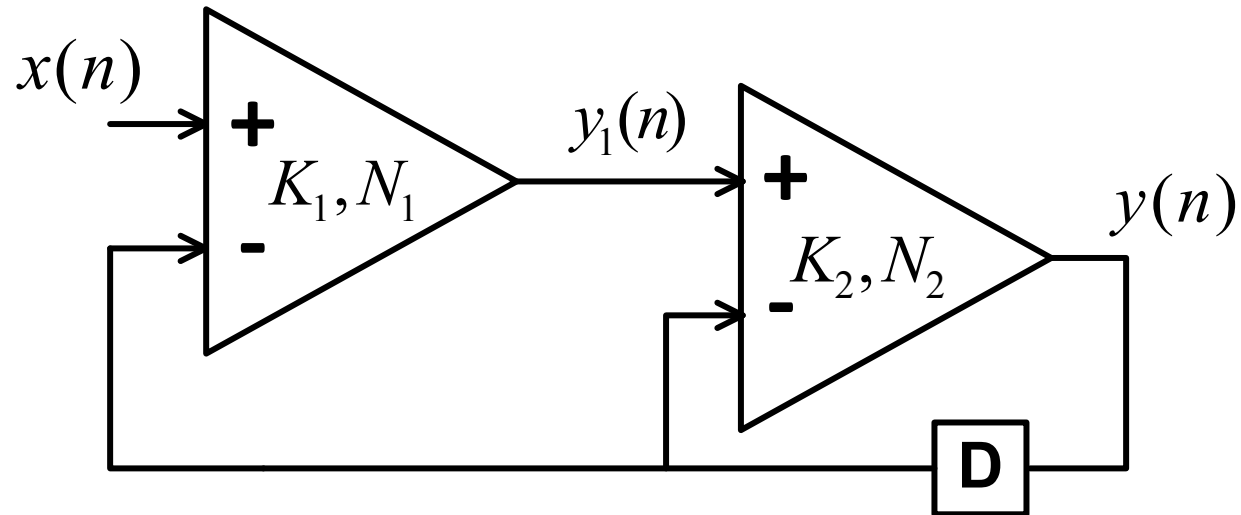
Order 1 Stochastic IIR Filter



$$H(z) = \frac{Y(z)}{X(z)} = \frac{K}{Nz + K - N}$$

$$p = 1 - K/N$$

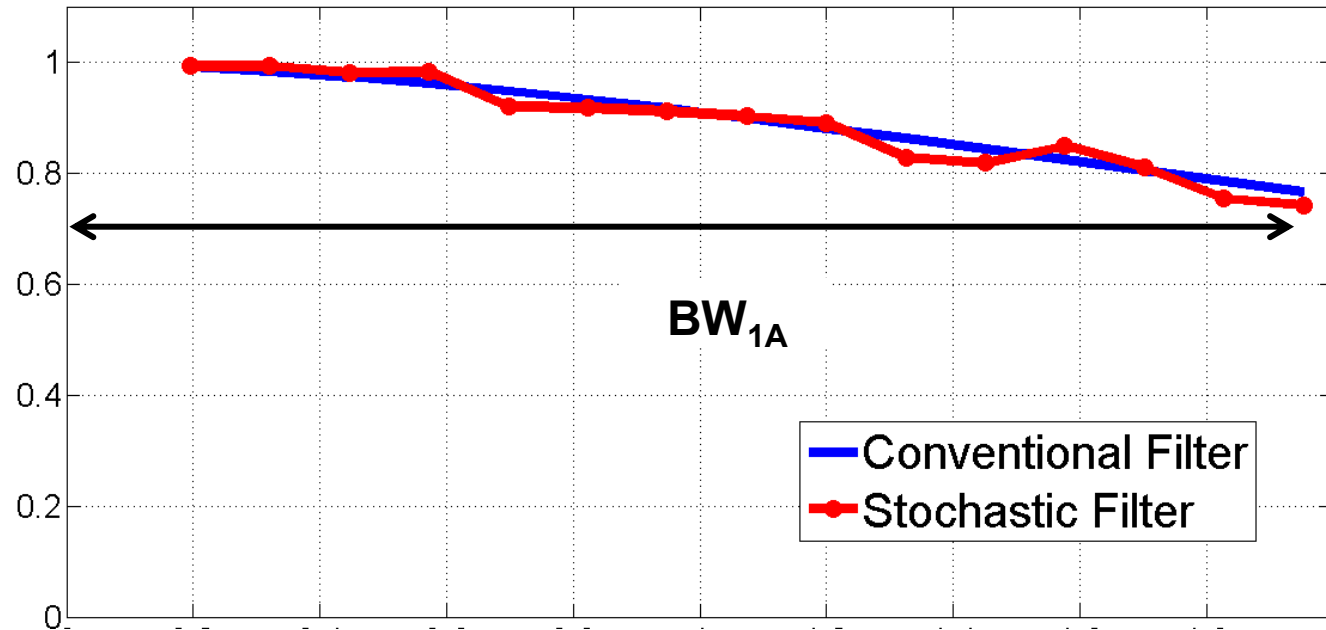
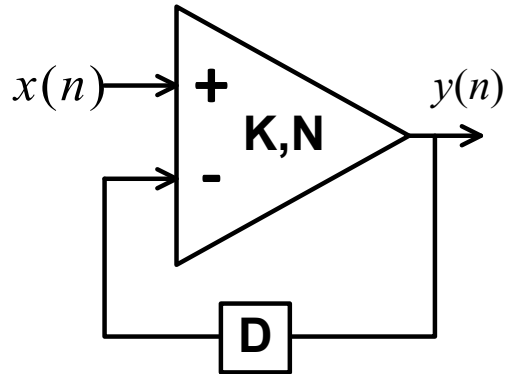
Order 2 Stochastic IIR Filter



$$H(z) = \frac{K_1 K_2}{N_1 N_2 z^2 + (N_1 K_2 - 2N_1 N_2)z + (N_1 N_2 - N_1 K_2 + K_1 K_2)}$$

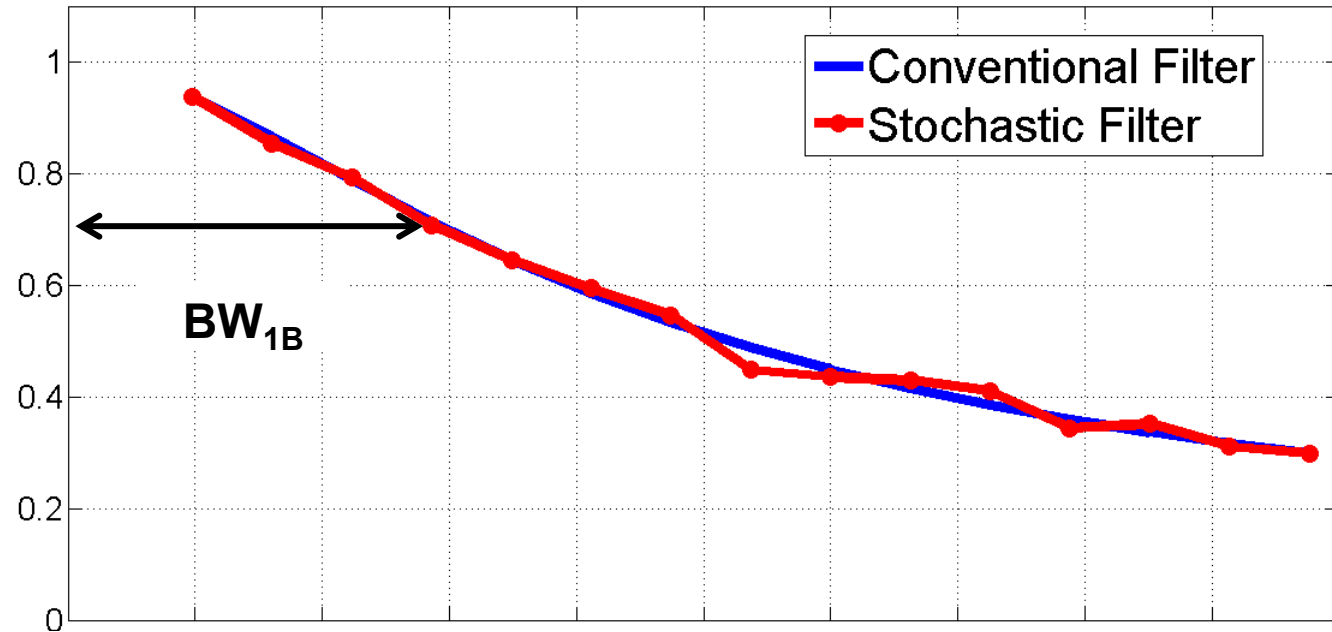
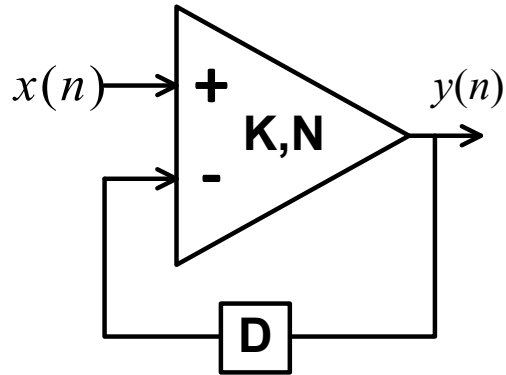
$$p_1, p_2 = 1 - \frac{K_2}{2N_2} \pm \sqrt{\frac{N_1^2 K_2^2 - 4N_1 N_2 K_1 K_2}{4N_1^2 N_2^2}}$$

Experiments: Order 1 Stochastic IIR Filters



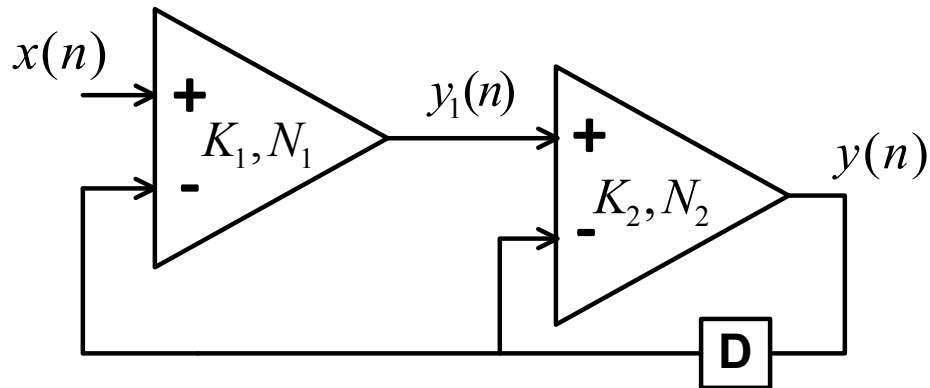
$$K_1 = 1, N_1 = 64, p_1 = 0.984$$

Experiments: Order 1 Stochastic IIR Filters

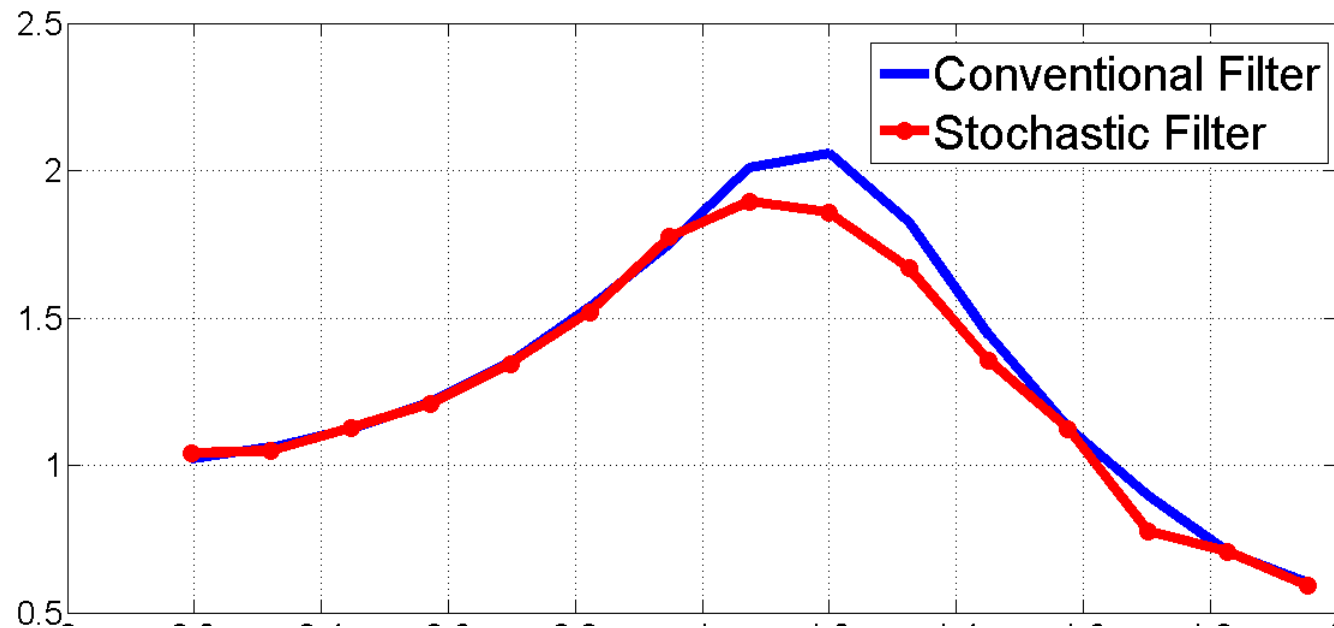


$$K_1 = 1, N_1 = 256, p_1 = 0.996$$

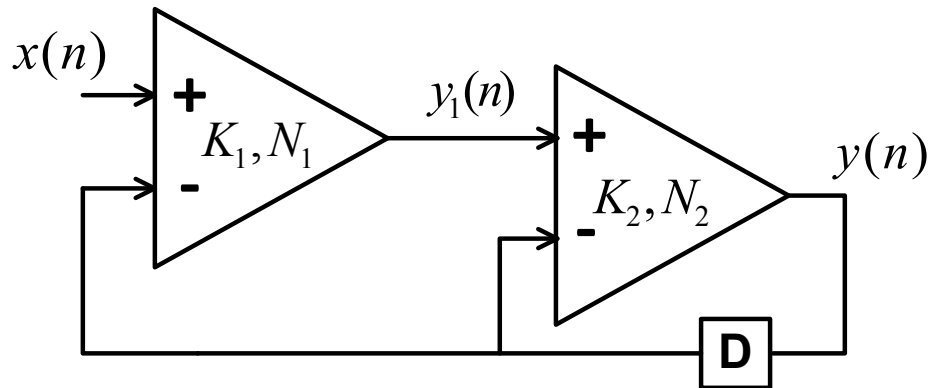
Experiments: Order 2 Stochastic IIR Filters



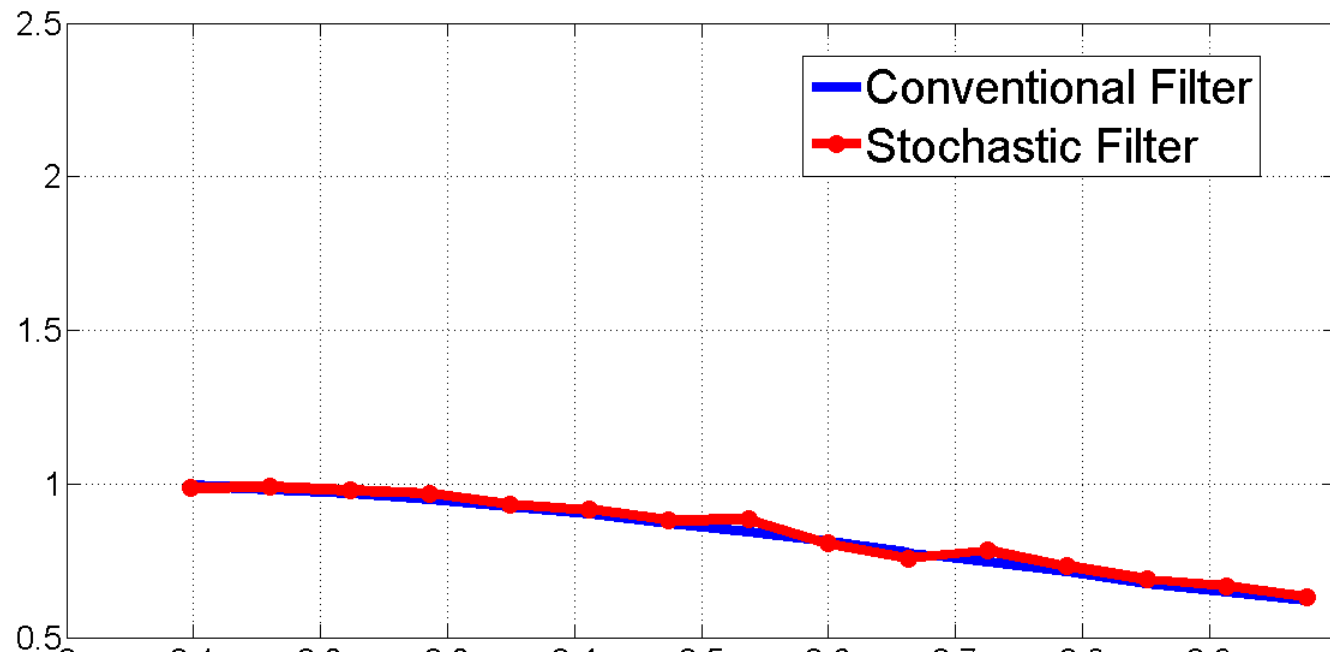
$$K_1 = 1, N_1 = 64,$$
$$K_2 = 1, N_2 = 256,$$
$$p_1 = 0.9980 + 0.0076i$$
$$p_2 = 0.9980 - 0.0076i$$



Experiments: Order 2 Stochastic IIR Filters



$$\begin{aligned} K_1 &= 1, N_1 = 64, \\ K_2 &= 1, N_2 = 256, \\ p_1 &= 0.9922 \\ p_2 &= 0.9922 \end{aligned}$$



Hardware Results

Order	K_1	N_1	K_2	N_2	Conventional	Stochastic
1	1	64	-	-	554	118.4
1	1	256	-	-	897.2	156.1
2	1	64	1	256	1067.4	270.0
2	1	256	1	64	1248.3	270.0

Conclusions and Future Research

- **Stochastic filtering: area efficiency**
- **Complicated noise analysis**
- **Bandpass/Highpass filters**